



Russian Research Center  
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# Negative energy waves and MHD stability of rotating plasma

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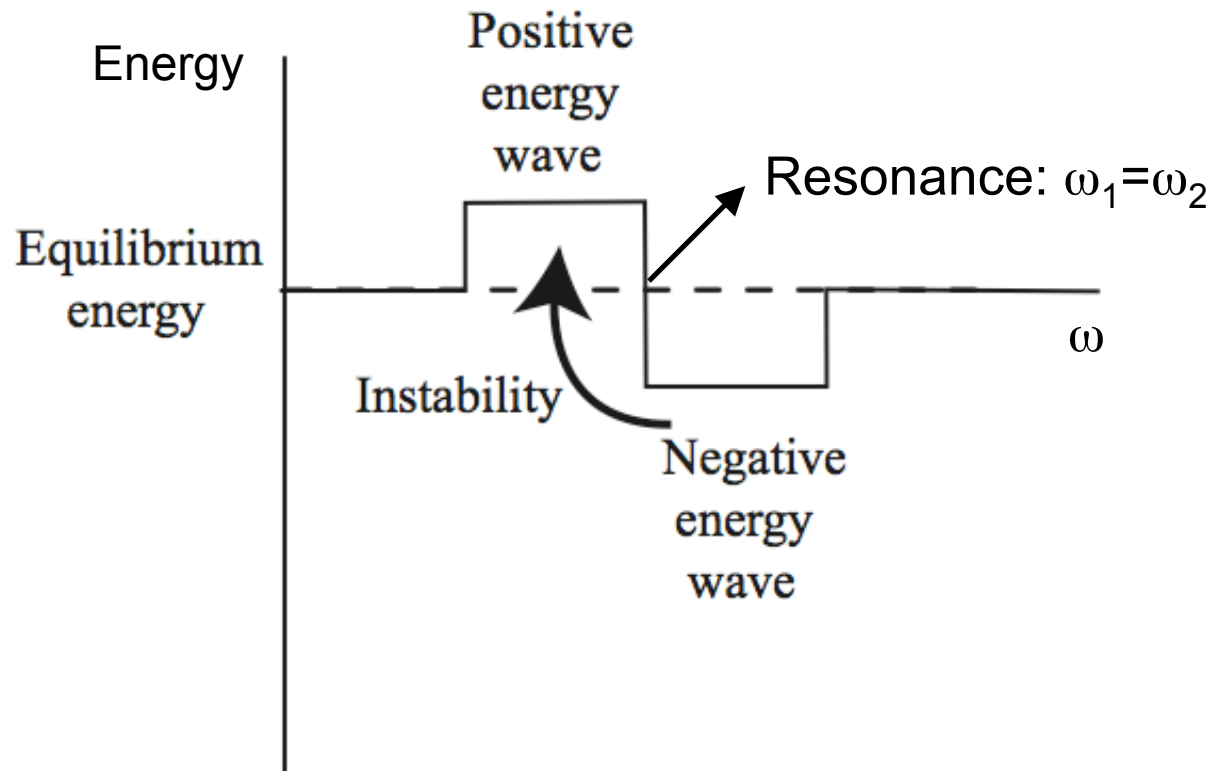
# Outline

- Introduction
- Energy of eigenmodes in ideal MHD
- Magnetorotational instability
- Modified energy principle
- Summary

# Introduction

- Energy consideration is of primary significance in MHD stability analysis
- Energy principle ( $\delta^2 W > 0$  for stability):
  - stability criterion for static systems (without flows)
  - only sufficient stability condition in moving media since waves with negative energy ( $\delta^2 W < 0$ ) can be excited
- Negative energy waves (NEWs) are potential source of instability. Classical examples:
  - hydrodynamical Kelvin-Helmholtz instability
  - plasma-beam instability
- Modified energy principle should be used to analyze stability of MHD systems with flows

# Positive and negative energy waves



- Excitation of NEW leads to decrease of total system energy
- PEW and NEW with frequencies  $\omega_1$  and  $\omega_2$  can coexist in the system
- When  $\omega_1 = \omega_2$  (resonance) energy can be transferred from NEW to PEW leading to instability

# Ideal MHD

$$\dot{\rho} = -\nabla \cdot (\rho \mathbf{V})$$

$$\rho \dot{\mathbf{V}} = -\rho(\mathbf{V} \cdot \nabla)\mathbf{V} - \nabla P + \frac{1}{4\pi} (\nabla \times \mathbf{B}) \times \mathbf{B}$$

$$\dot{P} = -\mathbf{V} \cdot \nabla P - \gamma P \nabla \cdot \mathbf{V}$$

$$\dot{\mathbf{B}} = \nabla \times (\mathbf{V} \times \mathbf{B}), \quad \nabla \cdot \mathbf{B} = 0$$

## Perturbations

$$\delta \mathbf{V} = \dot{\boldsymbol{\xi}} + (\mathbf{V} \cdot \nabla)\boldsymbol{\xi} - (\boldsymbol{\xi} \cdot \nabla)\mathbf{V}$$

$$\delta \rho = -\nabla \cdot (\rho \boldsymbol{\xi})$$

$$\delta P = -\boldsymbol{\xi} \cdot \nabla P - \gamma P \nabla \cdot \boldsymbol{\xi}$$

$$\delta \mathbf{B} = \nabla \times (\boldsymbol{\xi} \times \mathbf{B})$$

- $\boldsymbol{\xi}$  is a Lagrangian displacement vector

- Linearized equation of dynamics for  $\xi$ :

$$\rho \ddot{\xi} + 2\rho(\mathbf{V} \cdot \nabla)\dot{\xi} - \mathbf{F}(\xi) = 0$$

- Force operator:

$$\begin{aligned} \mathbf{F}(\xi) = & -\rho(\mathbf{V} \cdot \nabla)^2 \xi + \rho(\xi \cdot \nabla)(\mathbf{V} \cdot \nabla)\mathbf{V} + \nabla \cdot (\rho\xi)(\mathbf{V} \cdot \nabla)\mathbf{V} \\ & - \nabla \delta P + \frac{1}{4\pi} (\nabla \times \delta \mathbf{B}) \times \mathbf{B} + \frac{1}{4\pi} (\nabla \times \mathbf{B}) \times \delta \mathbf{B}. \end{aligned}$$

- Properties:

$$\int \eta \cdot \mathbf{F}(\xi) d^3 \mathbf{r} = \int \xi \cdot \mathbf{F}(\eta) d^3 \mathbf{r},$$

$$\int \rho \eta \cdot (\mathbf{V} \cdot \nabla)\xi d^3 \mathbf{r} = - \int \rho \xi \cdot (\mathbf{V} \cdot \nabla)\eta d^3 \mathbf{r}.$$

# Energy

$$E = \frac{1}{2} \int \left( \rho |\dot{\xi}|^2 - \xi^* \cdot \mathbf{F}(\xi) \right) d^3\mathbf{r}$$

Kinetic energy

Potential energy

- Energy is conserved:  $dE/dt = 0$

## Eigenvalue problem

$$\xi(\mathbf{r}, t) = \hat{\xi}(\mathbf{r}) e^{-i\omega t}$$

$$\omega^2 \rho \hat{\xi} + 2i\omega \rho (\mathbf{V} \cdot \nabla) \hat{\xi} + \mathbf{F}(\hat{\xi}) = 0$$

# Energy of eigenmode

$$A\omega^2 - 2B\omega - C = 0 \quad \omega = \frac{B + s\sqrt{B^2 + AC}}{A}$$

where either  $s = 1$  or  $s = -1$  for a particular eigenmode.

$$A = \int \rho |\hat{\xi}|^2 d^3\mathbf{r}, \quad B = -i \int \rho \hat{\xi}^* \cdot (\mathbf{V} \cdot \nabla) \hat{\xi} d^3\mathbf{r} \quad C = - \int \hat{\xi}^* \cdot \mathbf{F}(\hat{\xi}) d^3\mathbf{r}$$

- Energy:  $E = \frac{1}{2} (A|\omega|^2 + C)e^{2\gamma t} \quad \gamma = \text{Im}(\omega)$

- Unstable eigenmode:  $B^2 + AC < 0$

$$E = 0$$

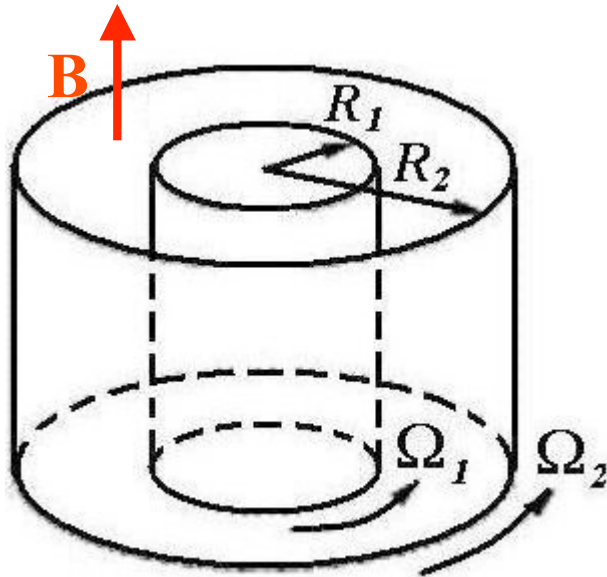
- Stable eigenmode:  $B^2 + AC > 0$

$$E = s\omega \sqrt{B^2 + AC}$$

- Energy of stable eigenmode can be either positive (PEW) or negative (NEW)

# Magnetorotational instability

- MRI is instability of conducting fluid rotating in transverse magnetic field



- Equilibrium:

$$\mathbf{B} = B_0 \mathbf{e}_z, \quad \mathbf{V} = r\Omega(r)\mathbf{e}_\phi, \quad \Omega(r) = \frac{\Omega_1 r_1^2}{r^2}$$

- Eigenmode representation:

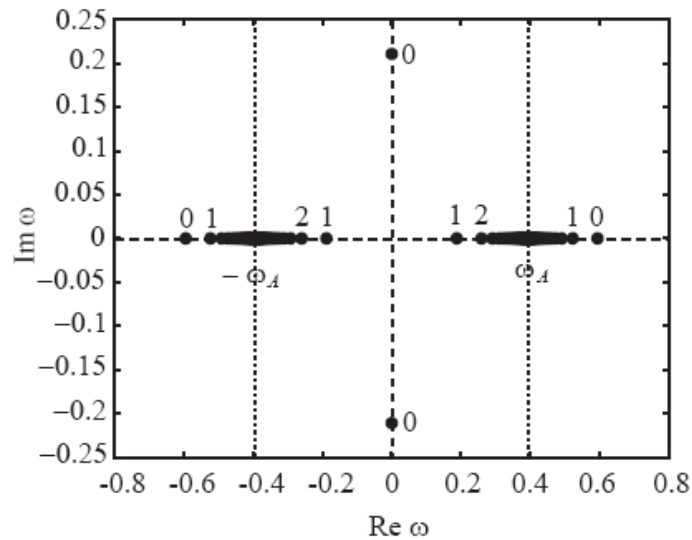
$$\xi(\mathbf{r}, t) = \xi(r) \exp(-i\omega t + im\phi + ik_z z).$$

- Alfvén frequency:

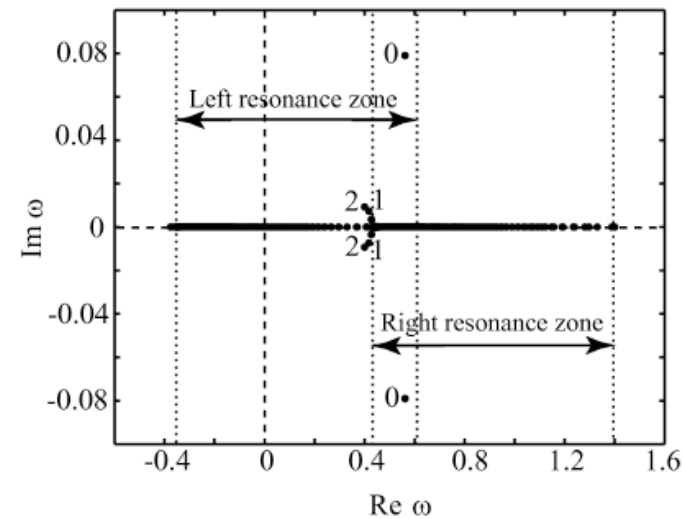
$$\omega_A = \frac{k_z B_0}{\sqrt{4\pi\rho}}.$$

# MRI eigen-spectrum

$m=0$

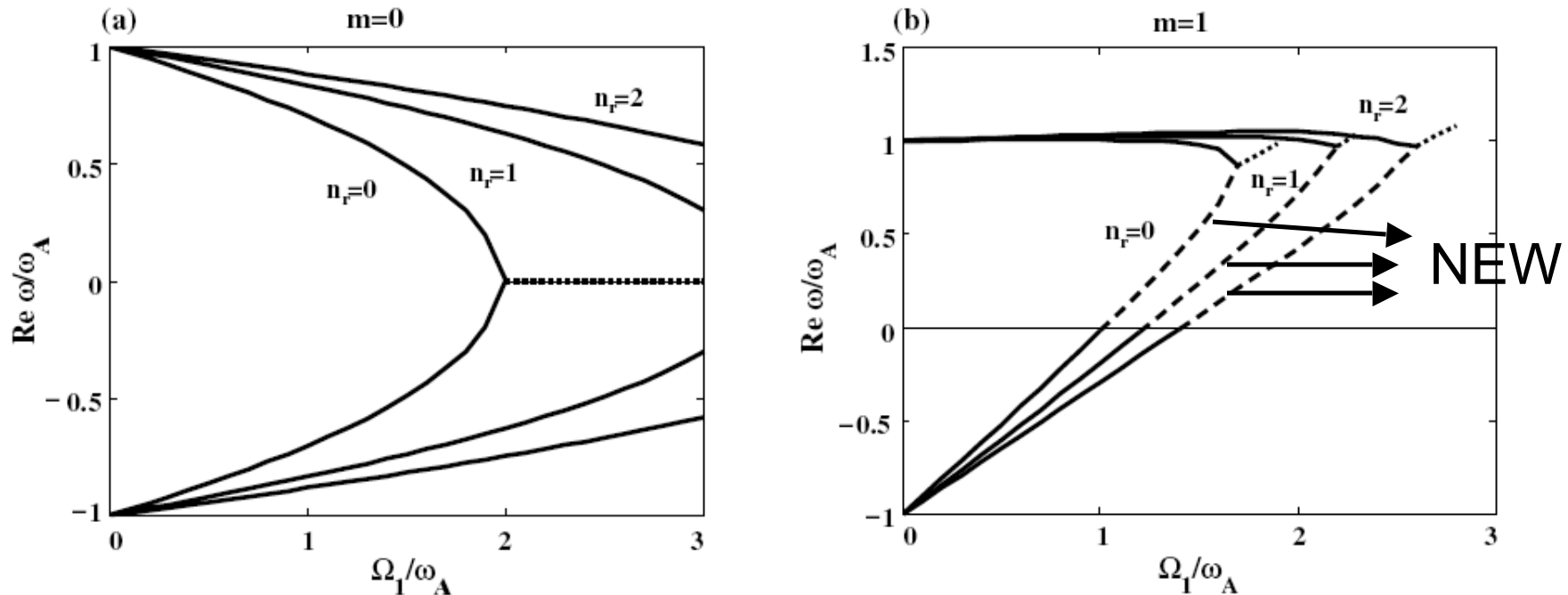


$m=1$



- Two types of eigenmodes are possible for general MHD systems with flows:
  - Symmetric (spectrum is symmetric about the origin)
  - Non-symmetric (spectrum is not symmetric about the imaginary axis)

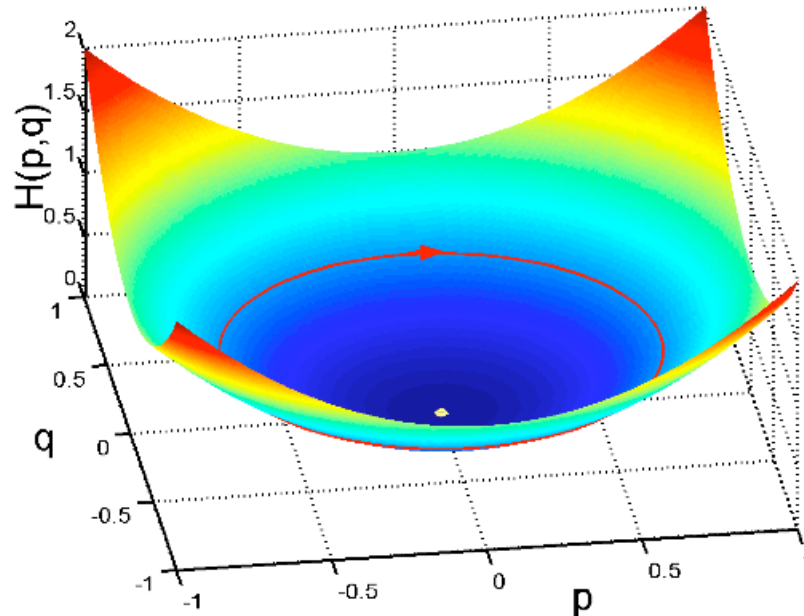
# Spectrum dependence on $\Omega_1/\omega_A$



- Energy of symmetric modes is never negative. Energy principle can be applied.
- Energy of stable non-symmetric modes can be negative. Modified energy principle should be used for their stability analysis

# What is the energy principle?

- Lyapunov theorem (sufficient stability condition):  
If there is an integral of motion (conserved quantity) which has a local minimum at the equilibrium state then the equilibrium is stable
- No general method to construct Lyapunov functional
- For conservative systems energy is a Lyapunov functional candidate.
- Example: oscillator with Hamiltonian (energy)  $H=p^2+q^2$  is stable



# Energy principle in ideal MHD

- Energy of perturbations (second variation of total energy):

$$E = \frac{1}{2} \int (\rho |\dot{\xi}|^2 - \xi^* \cdot \mathbf{F}(\xi)) d^3\mathbf{r}$$

- Energy principle (from Lyapunov theorem):

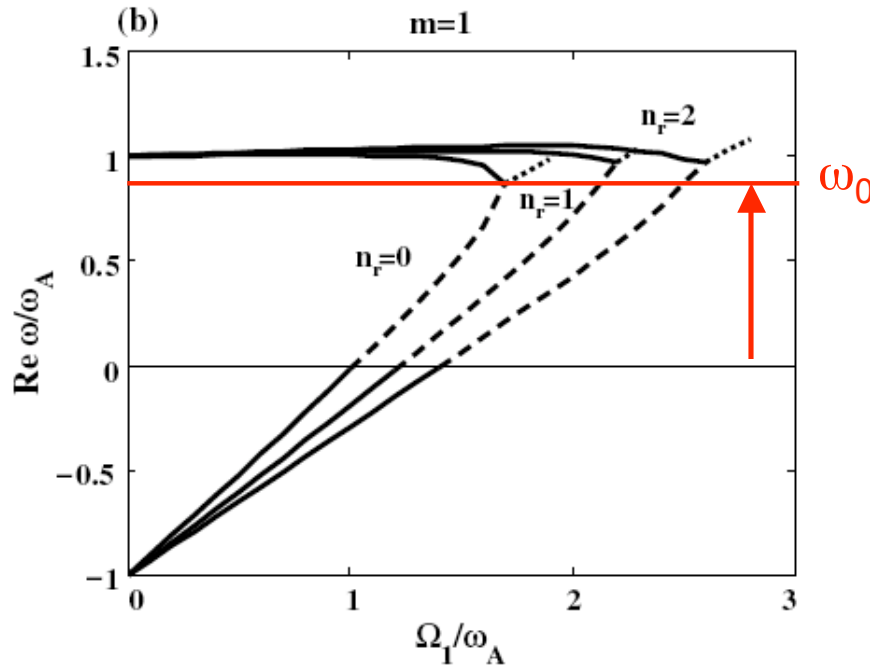
if potential energy

$$W(\xi) = -\frac{1}{2} \int \xi^* \cdot \mathbf{F}(\xi) d^3\mathbf{r} \geq 0$$

is positive for any displacement  $\xi$  then equilibrium is stable

- When  $\mathbf{V} = 0$  (no equilibrium flow) this condition is criterion (both sufficient and necessary) for stability
- When  $\mathbf{V} \neq 0$  this is only sufficient condition for stability.

# Modified energy principle for MRI

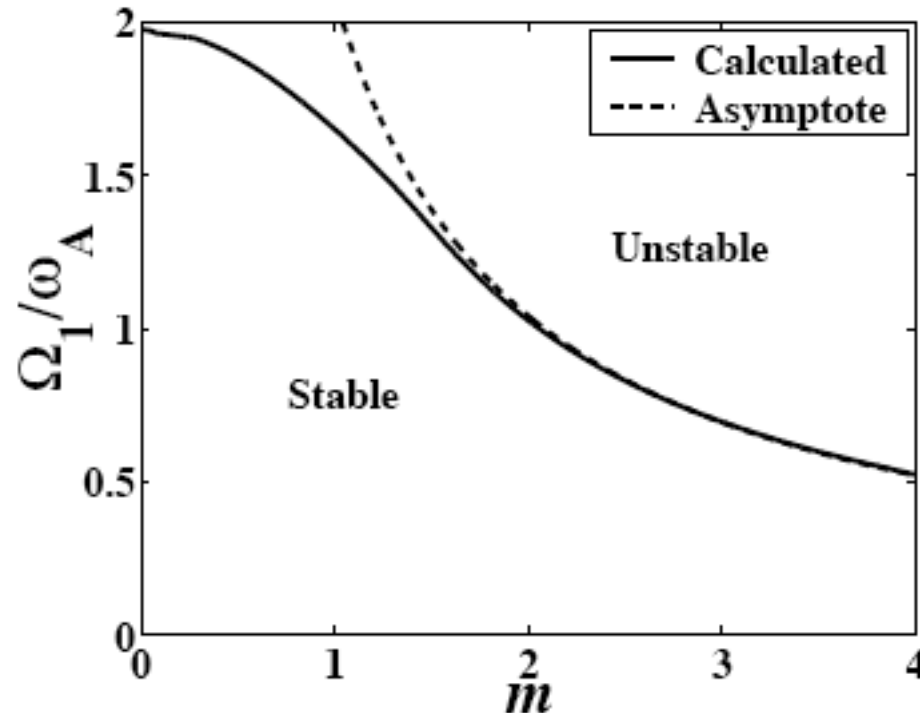


- Transition to reference frame rotating with frequency  $\omega_0$  eliminates all NEWs in stable system

- Then the usual energy principle applies: system is stable if potential energy (in moving reference frame) is positive for all perturbations

$$\begin{aligned} \tilde{W}(\xi) &= -\frac{1}{2} \int \xi^* \cdot \tilde{\mathbf{F}}(\xi) d^3\mathbf{r} = \\ &= -\frac{1}{2} \int \left( \omega_0^2 |\xi|^2 + 2i\omega_0 \rho \xi^* \cdot (\mathbf{V} \cdot \nabla) \xi + \xi^* \cdot \mathbf{F}(\xi) \right) d^3\mathbf{r}. \end{aligned}$$

# MRI threshold



- Modified energy principle gives the asymptote of MRI threshold (dashed line): 
$$\frac{\Omega_1}{\omega_A} = \frac{2}{m \left( 1 - (R_1/R_2)^2 \right)}$$
- Such simple modification of energy principle does not work for all MHD systems with flows.

# Summary

- The physical difference between symmetric and non-symmetric modes was demonstrated
- Resonance of positive and negative energy waves is a universal mechanism for any non-symmetric instability
- Modified energy principle was developed for stability study of systems with MHD flows
- Under certain assumptions this method gives both sufficient and necessary stability condition

# New invariants in ideal MHD

- Energy principle for the case  $\mathbf{V} \neq \mathbf{0}$  can be improved by inclusion of new invariants (conservation laws).

- Energy: 
$$E = \frac{1}{2} \int \left( \rho |\dot{\boldsymbol{\xi}}|^2 - \boldsymbol{\xi}^* \cdot \mathbf{F}(\boldsymbol{\xi}) \right) d^3\mathbf{r}$$

- New set of invariants ( $n$  is  $n$ -th time derivative):

$$E_n = \frac{1}{2} \int \left( \rho |\boldsymbol{\xi}^{(n+1)}|^2 - \boldsymbol{\xi}^{*(n)} \cdot \mathbf{F}(\boldsymbol{\xi}^{(n)}) \right) d^3\mathbf{r},$$

- No nonlinear analogues!
- Higher time derivatives of displacement vector  $\boldsymbol{\xi}^{(n)}$  are expressed via lower derivatives:

- For example: 
$$\boldsymbol{\xi}^{(n+2)} = -2(\mathbf{V} \cdot \nabla)\boldsymbol{\xi}^{(n+1)} + \frac{\mathbf{F}(\boldsymbol{\xi}^{(n)})}{\rho}$$

$$E_1(\dot{\boldsymbol{\xi}}, \boldsymbol{\xi}) = \frac{1}{2} \int \left( \frac{1}{\rho} \left| \mathbf{F}(\boldsymbol{\xi}) - 2\rho(\mathbf{V} \cdot \nabla)\dot{\boldsymbol{\xi}} \right|^2 - \dot{\boldsymbol{\xi}}^* \cdot \mathbf{F}(\dot{\boldsymbol{\xi}}) \right) d^3\mathbf{r}$$

# Improved energy principle

- Lyapunov functional candidate:

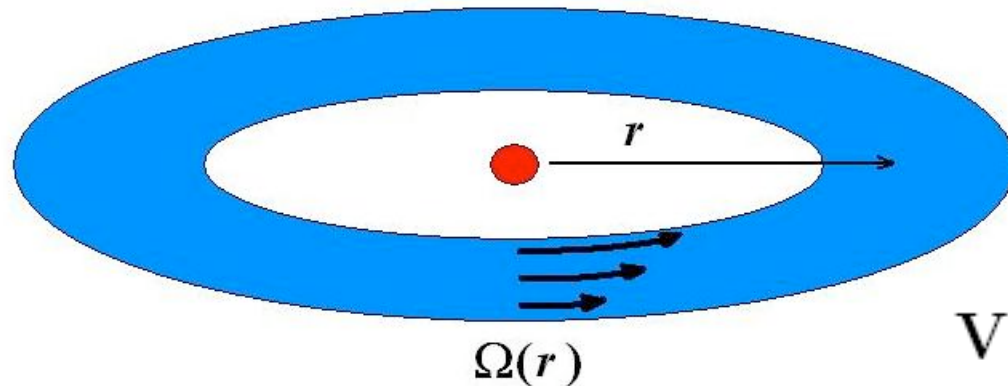
$$U(\dot{\xi}, \xi) = \sum_{n=0}^N \lambda_n E_n(\dot{\xi}, \xi)$$

- Improved energy principle:

If there exist Lagrange multipliers  $\lambda_n$  such that  $U$  is positively-definite for all displacements then equilibrium is stable

- For the systems with countable set of eigenmodes this gives also a necessary condition for stability

# Rotation of fluid in gravitational field



Equilibrium  
(no m. field):

$$\mathbf{V} = r\Omega(r)\mathbf{e}_\varphi, \quad r\Omega^2(r) = \Phi'$$

- Eigenmode stability analysis

$$\xi(t, \mathbf{r}) = \sum_{m, k_z} \xi_{m, k_z}(t, r) \exp\{im(\varphi - \Omega(r)t) + ik_z z\}$$

$$\ddot{\xi} + 2\Omega\hat{\mathbf{A}}\dot{\xi} - \hat{\mathbf{B}}\xi = 0$$

$$\hat{\mathbf{A}} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \hat{\mathbf{B}} = \begin{pmatrix} -r(\Omega^2)' & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

# Rayleigh criterion

- Spectral method gives:

$$4\Omega^2 + r(\Omega^2)' \geq 0$$

- The first two integrals:

$$E_0 = \frac{1}{2} \left( |\dot{\xi}|^2 - \xi^{*T} \hat{\mathbf{B}} \xi \right) = \frac{1}{2} \left( |\dot{\xi}_r|^2 + |\dot{\xi}_\varphi|^2 + |\dot{\xi}_z|^2 + r(\Omega^2)' |\xi_r|^2 \right).$$

$$\begin{aligned} E_1 &= \frac{1}{2} \left( |\hat{\mathbf{B}} \xi - 2\Omega \hat{\mathbf{A}} \dot{\xi}|^2 - \dot{\xi}^{*T} \hat{\mathbf{B}} \dot{\xi} \right) = \\ &= \frac{1}{2} \left( \left| r(\Omega^2)' \xi_r - 2\Omega \dot{\xi}_\varphi \right|^2 + \left( 4\Omega^2 + r(\Omega^2)' \right) |\dot{\xi}_r|^2 \right). \end{aligned}$$

- If we choose  $U=E_1$  we arrive at the same stability criterion